

<b>Form 1449 (Modified)</b>		<b>Atty Docket No.</b>	XENOP009
<b>Information Disclosure Statement By Applicant</b>		<b>Application No.:</b>	10/606,976
		<b>Applicant</b>	STEARNS et al.
		<b>Filing Date</b>	June 25, 2003
		<b>Group</b>	3768
(Use Several Sheets if Necessary)		Page 1 of 1	

**U.S. Patent Documents**

<b>Examiner Initial</b>	<b>No.</b>	<b>Patent No.</b>	<b>Date</b>	<b>Patentee</b>	<b>Class</b>	<b>Sub-class</b>	<b>Filing Date</b>
	1.						
	2.						
	3.						
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**Foreign Patent or Published Foreign Patent Application**

<b>Examiner Initial</b>		<b>Document No.</b>	<b>Publication Date</b>	<b>Country or Patent Office</b>	<b>Class</b>	<b>Sub-Class</b>	<b>Translation</b>
							<b>Yes</b> <b>No</b>
	6.						
	7.						
	8.						
	9.						

**Other Documents**

<b>Examiner Initial</b>	<b>No.</b>	<b>Author, Title, Place (e.g. Journal) of Publication, Date</b>
	10.	MOUADDIB et al., "Recent Progress in Structured Light in Order to Solve the Correspondence Problem in Stereo Vision", International Conference of Robotics and Automation, Albuquerque, New Mexico, April 1997 pps. 130-136
	11.	BATTLE et al., "Recent Progress in Coded Structured Light as a Technique to Solve the Correspondence Problem: A Survey", Pattern Recognition, Vol. 31, No. 7, 1998, pps. 963-982
	12.	FOFI et al., "Uncalibrated Vision Based on Structured Light", Proceedings of the 2001 IEEE International Conference on Robotics and Automation, Seoul, Korea, May 2001, pps. 3548-3553
	13.	SCHARSTEIN et al., "High-Accuracy Stereo Depth Maps Using Structured Light", IEEE Computer Society Conference on Computer Vision and Pattern Recognition (CVPR) 2003), Vol. 1, Madison, Wisconsin, pps. 195-202
	14.	
	15.	
	16.	

<b>Examiner</b>	<b>Date Considered</b>
/Vani Gupta/	05/01/2009

Examiner: Initial citation considered. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

**ALL REFERENCES CONSIDERED EXCEPT WHERE LINED THROUGH. /V.G./**